

## INFORMATION DISCLOSURE CITATION

Attorney Docket No.  
040894-7211

Application No.: 10/529,252

(Use several sheets if necessary)

Applicant(s): Shuuji KAJITA et al.

PAGE 1 of 1

PTO Form 1449

Filing Date: May 25, 2005

Group Art Unit: 3661 3664

## U.S. PATENT DOCUMENTS

*Examiner Initial	Document Number	Date	Name	Class	Sub Class	Filing Date

## FOREIGN PATENT DOCUMENTS

Document Number	Date	Country	Class	Sub Class	Translation YES NO
10-86081	April 7, 1998	Japan			Abstract

## OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, Etc.)

	Takanishi: Biped Walking Robot Compensating Moment by Trunk Motion, Journal of the Robotics Society of Japan, Vol. 11, No. 3, pp. 348-353 (1993).
	Nishiaki, Kitagawa, et al.: Fast Generation of a Dynamically Stable Trajectory of Humanoid with Linear Decoupling and discretization of ZMP Derivation - attained in Perception-Action Integrated Whole-Body Humanoid H6, The 18th Annual Conference of the Robotics Society of Japan, pp. 721-72 (2000).

Examiner /Modieunel Marc/

Date Considered /Modieunel Marc/

Examiner: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.